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Dynamics of Mechanical Systems - Harold Josephs 2002-06-19

Mechanical systems are becoming increasingly sophisticated and continually require greater precision, improved reliability, and extended life. To meet the demand for advanced mechanisms and systems, present and future engineers must understand not only the fundamental mechanical components, but also the principles of vibrations, stability, and balance and the use of Newton's laws, Lagrange's equations, and Kane's methods. Dynamics of Mechanical Systems provides a vehicle for mastering all of this. Focusing on the fundamental procedures behind dynamic analyses, the authors take a vector-oriented approach and lead readers methodically from simple concepts and systems through the analysis of complex robotic and bio-systems. A careful presentation that balances theory, methods, and applications gives readers a working knowledge of configuration graphs, Euler parameters, partial velocities and partial angular velocities, generalized speeds and forces, lower body arrays, and Kane's equations. Evolving from more than three decades of teaching upper-level engineering courses, Dynamics of Mechanical Systems enables readers to obtain and refine skills ranging from the ability to perform insightful hand analyses to developing algorithms for numerical/computer analyses. Ultimately, it prepares them to solve real-world problems and make future advances in mechanisms, manipulators, and robotics.

Mechanical Systems, Classical Models - Petre P. Teodorescu 2010-11-19

As it was already seen in the first volume of the present book, its guideline is precisely the mathematical model of mechanics. The classical models which we refer to are in fact models based on the Newtonian model of mechanics, on its five principles, i. e. : the inertia, the forces action, the action and reaction, the parallelogram and the initial conditions principle, respectively. Other models, e. g. , the model of attraction forces between the particles of a discrete mechanical system, are part of the considered Newtonian model. Kepler's laws brilliantly verify this model in case of velocities much smaller than the light velocity in vacuum. The non-classical models are relativistic and quantic. Mechanics has as object of study mechanical systems. The first volume of this book dealt with particle dynamics. The present one deals with discrete mechanical systems for particles in a number greater than the unity, as well as with continuous mechanical systems. We put in evidence the difference between these models, as well as the specificity of the corresponding studies; the generality of the proofs and of the corresponding computations yields a common form of the obtained mechanical results for both discrete and continuous systems. We mention the thoroughness by which the dynamics of the rigid solid with a fixed point has been presented. The discrete or continuous mechanical systems can be non-deformable (e. g.

Bulletin - Institute of Mathematics and Its Applications 1983

Scientific and Technical Aerospace Reports - 1993

Effect of Mass Variation on the Attitude Motion of Rocket Systems - Michael J. Morris 2001

Impact Mechanics - W. J. Stronge 2018-11-15

This second edition of Impact Mechanics offers new analytical methods with examples for the dynamics of low-speed impact.

Statistical Dynamics and Reliability Theory for Mechanical Structures - Valery A. Svetlitsky 2012-12-06

The monograph text is based on lectures delivered by author during many years for students of Applied Iechanics Department of Bauman Ioscow State Technical University. The monograph includes also analitical results of scientific research obtained in collaboration with industry. Progress in developing new equipment has called for a better understand ing of the physical peculiarities pertaining to the action of designed structures in real conditions. This is necessary for increasing the accuracy of the analysis and making these structures more reliable. It has been found that classical determined perturbations are not principal and that determinism-based methods of classical mechanics prove insufficient for understanding and explaining physical effects that arise at the operation of instruments located on moving objects, the vibration of rocket engines, the motion of a vehicle, and the action of wind and seismic loads. Therefore the necessity arose for devising a new physical model to analyze these dynamic processes and, in particular, for creating a new mathematical apparatus that would allow us to take into account non-deterministic external excitations. The theory of random processes that had been developed well enough as applied to problems of radio engineering and automatic control, where the effect produced by random excitations appeared to be commensurable with that of deterministic excitations and where the ignoring of the random ex citations would bring about incorrect results, became such an apparatus.

System Dynamics for Engineering Students - Nicolae Lobontiu 2017-08-29

Engineering system dynamics focuses on deriving mathematical models based on simplified physical representations of actual systems, such as mechanical, electrical, fluid, or thermal, and on solving these models for analysis or design purposes. System Dynamics for Engineering Students: Concepts and Applications features a classical approach to system dynamics and is designed to be utilized as a one-semester system dynamics text for upper-level undergraduate students with emphasis on mechanical, aerospace, or electrical engineering. It is the first system dynamics textbook to include examples from compliant (flexible) mechanisms and micro/nano electromechanical systems (MEMS/NEMS). This new second edition has been updated to provide more balance between analytical and computational approaches; introduces additional in-text coverage of Controls; and includes numerous fully solved examples and exercises. Features a more balanced treatment of mechanical, electrical, fluid, and thermal systems than other texts Introduces examples from compliant (flexible) mechanisms and MEMS/NEMS

Includes a chapter on coupled-field systems Incorporates MATLAB® and Simulink® computational software tools throughout the book Supplements the text with extensive instructor support available online: instructor's solution manual, image bank, and PowerPoint lecture slides NEW FOR THE SECOND EDITION Provides more balance between analytical and computational approaches, including integration of Lagrangian equations as another modelling technique of dynamic systems Includes additional in-text coverage of Controls, to meet the needs of schools that cover both controls and system dynamics in the course Features a broader range of applications, including additional applications in pneumatic and hydraulic systems, and new applications in aerospace, automotive, and bioengineering systems, making the book even more appealing to mechanical engineers Updates include new and revised examples and end-of-chapter exercises with a wider variety of engineering applications

IUTAM Symposium on Recent Advances in Moving Boundary Problems in Mechanics - Stefanie Gutschmidt 2019

Many problems in mechanics involve deformable domains with moving boundaries, including fluid-structure interaction, multiphase flows, flows over soft tissues and textiles, or flows involving accretion/erosion to name but a few. The presence of a moving boundary presents considerable challenges when it comes to modelling and understanding the underlying system dynamics. This proceedings volume collects contributions made at the IUTAM Symposium on Recent Advances in Moving Boundary Problems in Mechanics held in Christchurch, New Zealand in February 2018.

Dynamics of Machines with Variable Mass - L Cveticanin 1998-10-21

Designed to be a complete and integrated text on the dynamic properties of machines, mechanisms, and rotors with variable mass, this book presents new results from investigations based on the general dynamics of systems with variable parameters. The book considers both weak and strong nonlinear vibrations of these systems, and chaotic phenomena are also discussed. The conservation laws and adiabatic invariants for systems with variable mass are formulated and the stability and instability conditions of motion are defined.

The Mechanics Problem Solver - Research and Education Association 1995

Advances in Mechanical Systems Dynamics - Alberto Doria 2020-02-13

Modern dynamics was established many centuries ago by Galileo and Newton before the beginning of the industrial era. Presently, we are in the presence of the fourth industrial revolution, and mechanical systems are increasingly being integrated with electronic, electrical, and fluidic systems. This trend is present not only in the industrial environment, which will soon be characterized by the cyber-physical systems of industry 4.0, but also in other environments like mobility, health and bio-engineering, food and natural resources, safety, and sustainable living. In this context, purely mechanical systems with quasi-static behavior will become less common and the state-of-the-art will soon be represented by integrated mechanical systems, which need accurate dynamic models to predict their behavior. Therefore, mechanical system dynamics are going to play an increasingly central role. Significant research efforts are needed to improve the identification of the mechanical properties of systems in order to develop models that take non-linearity into account, and to develop efficient simulation tools. This Special Issue aims at disseminating the latest research achievements, findings, and ideas in mechanical systems dynamics, with particular emphasis on applications that are strongly integrated with other systems and require a multi-physical approach.

Feedback Systems - Karl Johan Åström 2021-02-02

The essential introduction to the principles and applications of feedback systems—now fully revised and expanded This textbook covers the mathematics needed to model, analyze, and design feedback systems. Now more user-friendly than ever, this revised and expanded edition of *Feedback Systems* is a one-volume resource for students and researchers in mathematics and engineering. It has applications across a range of disciplines that utilize feedback in physical, biological, information, and economic systems. Karl Åström and Richard Murray use techniques from physics, computer science, and operations research to introduce control-oriented modeling. They begin with state space tools for analysis and design, including stability of solutions, Lyapunov functions, reachability, state feedback observability, and estimators. The matrix

exponential plays a central role in the analysis of linear control systems, allowing a concise development of many of the key concepts for this class of models. Åström and Murray then develop and explain tools in the frequency domain, including transfer functions, Nyquist analysis, PID control, frequency domain design, and robustness. Features a new chapter on design principles and tools, illustrating the types of problems that can be solved using feedback Includes a new chapter on fundamental limits and new material on the Routh-Hurwitz criterion and root locus plots Provides exercises at the end of every chapter Comes with an electronic solutions manual An ideal textbook for undergraduate and graduate students Indispensable for researchers seeking a self-contained resource on control theory

Tensor Calculus and Analytical Dynamics - John G. Papastavridis 2018-12-12

Tensor Calculus and Analytical Dynamics provides a concise, comprehensive, and readable introduction to classical tensor calculus - in both holonomic and nonholonomic coordinates - as well as to its principal applications to the Lagrangean dynamics of discrete systems under positional or velocity constraints. The thrust of the book focuses on formal structure and basic geometrical/physical ideas underlying most general equations of motion of mechanical systems under linear velocity constraints. Written for the theoretically minded engineer, Tensor Calculus and Analytical Dynamics contains uniquely accessible treatments of such intricate topics as: tensor calculus in nonholonomic variables Pfaffian nonholonomic constraints related integrability theory of Frobenius The book enables readers to move quickly and confidently in any particular geometry-based area of theoretical or applied mechanics in either classical or modern form.

Mechanical Vibrations: Theory and Applications - Kelly 2012-07-27

Mechanical Vibrations: Theory and Applications takes an applications-based approach at teaching students to apply previously learned engineering principles while laying a foundation for engineering design. This text provides a brief review of the principles of dynamics so that terminology and notation are consistent and applies these principles to derive mathematical models of dynamic mechanical systems. The methods of application of these principles are consistent with popular Dynamics texts. Numerous pedagogical features have been included in the text in order to aid the student with comprehension and retention. These include the development of three benchmark problems which are revisited in each chapter, creating a coherent chain linking all chapters in the book. Also included are learning outcomes, summaries of key concepts including important equations and formulae, fully solved examples with an emphasis on real world examples, as well as an extensive exercise set including objective-type questions. Important Notice: Media content referenced within the product description or the product text may not be available in the ebook version.

Applied Mechanics Reviews - 1974

Classical Mechanics - Jan Awrejcewicz 2012-07-12

This is the second volume of three books devoted to Mechanics. In this book, dynamical and advanced mechanics problems are stated, illustrated, and discussed, including a few novel concepts in comparison to standard text books and monographs. Apart from being addressed to a wide spectrum of graduate students, postgraduate students, researchers, and teachers from the fields of mechanical and civil engineering, this volume is also intended to be used as a self-contained material for applied mathematicians and physical scientists and researchers.

Nonlinear Dynamics of Production Systems - Günter Radons 2006-03-06

This reference work provides a comprehensive insight into past developments in the application of non-linear dynamics, such as production systems in the manufacturing and process engineering, mechanical engineering and plant construction and automation technology. As such, it is the first publication to document the successful implementation of non-linear dynamics into current tasks or problems of engineering thus far unsolved. The interdisciplinary team of contributors from research and industry establishes ties between mechanical methods of manufacturing and new methods reaching the dynamics of production lines and complete production systems.

Acoustics and Vibration of Mechanical Structures—AVMS 2019 - Nicolae Herisanu 2020-11-19

This book contains selected and expanded contributions presented at the 15th Conference on Acoustics and

Vibration of Mechanical Structures held in Timisoara, Romania, May 30-31, 2019. The conference focused on a broad range of topics related to acoustics and vibration, such as analytical approaches to nonlinear noise and vibration problems, environmental and occupational noise, structural vibration, biomechanics and bioacoustics, as well as experimental approaches to vibration problems in industrial processes. The different contributions also address the analytical, numerical and experimental techniques applicable to analyze linear and non-linear noise and vibration problems (including strong nonlinearity) and they are primarily intended to emphasize the actual trends and state-of-the-art developments in the above mentioned topics. The book is meant for academics, researchers and professionals, as well as PhD students concerned with various fields of acoustics and vibration of mechanical structures.

Attitude Dynamics of Variable Mass Systems - Songmin Wang 1993

Dynamics of Bodies with Time-Variable Mass - Livija Cveticanin 2015-07-31

This book deals with the problem of dynamics of bodies with time-variable mass and moment of inertia. Mass addition and mass separation from the body are treated. Both aspects of mass variation, continual and discontinual, are considered. Dynamic properties of the body are obtained applying principles of classical dynamics and also analytical mechanics. Advantages and disadvantages of both approaches are discussed. Dynamics of constant body is adopted, and the characteristics of the mass variation of the body is included. Special attention is given to the influence of the reactive force and the reactive torque. The vibration of the body with variable mass is presented. One and two degrees of freedom oscillators with variable mass are discussed. Rotors and the Van der Pol oscillator with variable mass are displayed. The chaotic motion of bodies with variable mass is discussed too. To support learning, some solved practical problems are included.

Proceedings of the 10th International Conference on Rotor Dynamics - IFToMM - Katia Lucchesi Cavalca 2018-08-18

IFToMM conferences have a history of success due to the various advances achieved in the field of rotor dynamics over the past three decades. These meetings have since become a leading global event, bringing together specialists from industry and academia to promote the exchange of knowledge, ideas, and information on the latest developments in the dynamics of rotating machinery. The scope of the conference is broad, including e.g. active components and vibration control, balancing, bearings, condition monitoring, dynamic analysis and stability, wind turbines and generators, electromechanical interactions in rotor dynamics and turbochargers. The proceedings are divided into four volumes. This third volume covers the following main topics: dynamic analysis and stability; electromechanical interactions in rotordynamics; nonlinear phenomena in rotordynamics; rotordynamics of micro, nano and cryogenic machines; and fluid structure interactions in rotordynamics.

System Dynamics and Mechanical Vibrations - Dietmar Findeisen 2000-08-15

A comprehensive treatment of "linear systems analysis" applied to dynamic systems as an approach to interdisciplinary system design beyond the related area of electrical engineering. The text gives an interpretation of mechanical vibrations based on the theory of dynamic systems, aiming to bridge the gap between existing theoretical methods in different engineering disciplines and to enable advanced students or professionals to model dynamic and vibrating systems with reference to communication and control processes. Emphasizing the theory it presents a balanced coverage of analytical principles and applications to vibrations with regard to mechatronic problems.

Classical Mechanics - Jan Awrejcewicz 2014-08-08

This is the second volume of three books devoted to Mechanics. In this book, dynamical and advanced mechanics problems are stated, illustrated, and discussed, including a few novel concepts in comparison to standard text books and monographs. Apart from being addressed to a wide spectrum of graduate students, postgraduate students, researchers, and teachers from the fields of mechanical and civil engineering, this volume is also intended to be used as a self-contained material for applied mathematicians and physical scientists and researchers.

Applied Structural and Mechanical Vibrations - Paolo L. Gatti 2014-02-24

The second edition of Applied Structural and Mechanical Vibrations: Theory and Methods continues the

first edition's dual focus on the mathematical theory and the practical aspects of engineering vibrations measurement and analysis. This book emphasises the physical concepts, brings together theory and practice, and includes a number of worked-out examples of varying difficulty and an extensive list of references. What's New in the Second Edition: Adds new material on response spectra Includes revised chapters on modal analysis and on probability and statistics Introduces new material on stochastic processes and random vibrations The book explores the theory and methods of engineering vibrations. By also addressing the measurement and analysis of vibrations in real-world applications, it provides and explains the fundamental concepts that form the common background of disciplines such as structural dynamics, mechanical, aerospace, automotive, earthquake, and civil engineering. Applied Structural and Mechanical Vibrations: Theory and Methods presents the material in order of increasing complexity. It introduces the simplest physical systems capable of vibratory motion in the fundamental chapters, and then moves on to a detailed study of the free and forced vibration response of more complex systems. It also explains some of the most important approximate methods and experimental techniques used to model and analyze these systems. With respect to the first edition, all the material has been revised and updated, making it a superb reference for advanced students and professionals working in the field.

IUTAM Symposium on Recent Advances in Moving Boundary Problems in Mechanics - Stefanie Gutschmidt 2019-03-28

Many problems in mechanics involve deformable domains with moving boundaries, including fluid-structure interaction, multiphase flows, flows over soft tissues and textiles, or flows involving accretion/erosion to name but a few. The presence of a moving boundary presents considerable challenges when it comes to modelling and understanding the underlying system dynamics. This proceedings volume collects contributions made at the IUTAM Symposium on Recent Advances in Moving Boundary Problems in Mechanics held in Christchurch, New Zealand in February 2018.

Classical and Analytical Mechanics - Alex Poznyak 2021-04-08

Classical and Analytical Mechanics: Theory, Applied Examples, and Practice provides a bridge between the theory and practice related to mechanical, electrical, and electromechanical systems. It includes rigorous mathematical and physical explanations while maintaining an interdisciplinary engineering focus. Applied problems and exercises in mechanical, mechatronic, aerospace, electrical, and control engineering are included throughout and the book provides detailed techniques for designing models of different robotic, electrical, defense, and aerospace systems. The book starts with multiple chapters covering kinematics before moving onto coverage of dynamics and non-inertial and variable mass systems. Euler's dynamic equations and dynamic Lagrange equations are covered next with subsequent chapters discussing topics such as equilibrium and stability, oscillation analysis, linear systems, Hamiltonian formalism, and the Hamilton-Jacobi equation. The book concludes with a chapter outlining various electromechanical models that readers can implement and adapt themselves. Bridges theory and practice by providing readers techniques for solving common problems through mechanical, electrical, and electromechanical models alongside the underlying theoretical foundations Describes variable mass, non-inertial systems, dynamic Euler's equations, gyroscopes, and other related topics Includes a broad offering of practical examples, problems, and exercises across an array of engineering disciplines

Computer Aided Kinematics and Dynamics of Mechanical Systems: Basic methods - Edward J. Haug 1989

Dynamics of Mechanical Systems with Variable Mass - Hans Irschik 2016-08-23

The book presents up-to-date and unifying formulations for treating dynamics of different types of mechanical systems with variable mass. The starting point is overview of the continuum mechanics relations of balance and jump for open systems from which extended Lagrange and Hamiltonian formulations are derived. Corresponding approaches are stated at the level of analytical mechanics with emphasis on systems with a position-dependent mass and at the level of structural mechanics. Special emphasis is laid upon axially moving structures like belts and chains and on pipes with an axial flow of fluid. Constitutive relations in the dynamics of systems with variable mass are studied with particular reference to modeling of multi-component mixtures. The dynamics of machines with a variable mass are treated in detail and conservation laws and the stability of motion will be analyzed. Novel finite element

formulations for open systems in coupled fluid and structural dynamics are presented.

Advanced Multibody System Dynamics - Werner Schiehlen 2013-04-17

The German Research Council (DFG) decided 1987 to establish a nationwide five year research project devoted to dynamics of multibody systems. In this project universities and research centers cooperated with the goal to develop a general purpose multibody system software package. This concept provides the opportunity to use a modular structure of the software, i.e. different multibody formalisms may be combined with different simulation programmes via standardized interfaces. For the DFG project the database RSYST was chosen using standard FORTRAN 77 and an object oriented multibody system datamodel was defined. The project included • research on the fundamentals of the method of multibody systems, • concepts for new formalisms of dynamical analysis, • development of efficient numerical algorithms and • realization of a powerful software package of multibody systems. These goals required an interdisciplinary cooperation between mathematics, computer science, mechanics, and control theory. ix X After a rigorous reviewing process the following research institutions participated in the project (under the responsibility of leading scientists): Technical University of Aachen (Prof. G. Sedlacek) Technical University of Darmstadt (Prof. P. Hagedorn) University of Duisburg M. Hiller) (Prof.

Variational Principles in Classical Mechanics - Douglas Cline 2018-08

Two dramatically different philosophical approaches to classical mechanics were proposed during the 17th - 18th centuries. Newton developed his vectorial formulation that uses time-dependent differential equations of motion to relate vector observables like force and rate of change of momentum. Euler, Lagrange, Hamilton, and Jacobi, developed powerful alternative variational formulations based on the assumption that nature follows the principle of least action. These variational formulations now play a pivotal role in science and engineering. This book introduces variational principles and their application to classical mechanics. The relative merits of the intuitive Newtonian vectorial formulation, and the more powerful variational formulations are compared. Applications to a wide variety of topics illustrate the intellectual beauty, remarkable power, and broad scope provided by use of variational principles in physics. The second edition adds discussion of the use of variational principles applied to the following topics: (1) Systems subject to initial boundary conditions (2) The hierarchy of related formulations based on action, Lagrangian, Hamiltonian, and equations of motion, to systems that involve symmetries. (3) Non-conservative systems. (4) Variable-mass systems. (5) The General Theory of Relativity. Douglas Cline is a Professor of Physics in the Department of Physics and Astronomy, University of Rochester, Rochester, New York.

Friction Dynamics - Xiandong Liu 2016-07-20

Friction Dynamics: Principles and Applications introduces readers to the basic principles of friction dynamics, which are presented in a unified theoretical framework focusing on some of the most important engineering applications. The book's chapters introduce basic concepts and analytical methods of friction dynamics, followed by sections that explore the fundamental principles of frictions. Concluding chapters focus on engineering applications in brake dynamics, the friction dynamics of rods used in oil suck pump systems, and the friction impact dynamics of rotors. This book provides comprehensive topics and up-to-date results, also presenting a thorough account of important advancements in friction dynamics which offer insights into varied dynamic phenomena, helping readers effectively design and fabricate stable and durable friction systems and components for various engineering and scientific friction dynamical systems. Investigates the most critical engineering and scientific applications Provides the most comprehensive reference of its kind Offers a systematic treatment and a unified framework Explores cutting-edge methodologies to address non-stationary, non-linear dynamics and control

Dynamics of Mechanical Systems with Variable Mass - Hans Irschik 2014-10-16

The book presents up-to-date and unifying formulations for treating dynamics of different types of mechanical systems with variable mass. The starting point is overview of the continuum mechanics relations of balance and jump for open systems from which extended Lagrange and Hamiltonian formulations are derived. Corresponding approaches are stated at the level of analytical mechanics with emphasis on systems with a position-dependent mass and at the level of structural mechanics. Special emphasis is laid upon axially moving structures like belts and chains and on pipes with an axial flow of

fluid. Constitutive relations in the dynamics of systems with variable mass are studied with particular reference to modeling of multi-component mixtures. The dynamics of machines with a variable mass are treated in detail and conservation laws and the stability of motion will be analyzed. Novel finite element formulations for open systems in coupled fluid and structural dynamics are presented.

Applied Nonlinear Dynamics and Chaos of Mechanical Systems with Discontinuities - Marian Wiercigroch 2000

Annotation Consisting primarily of contributions written by engineers from Europe, Asia, and the US, this volume provides a general methodology for describing, solving, and analyzing discontinuous systems. The focus is on mechanical engineering problems where clearances, piecewise stiffness, intermittent contact, variable friction, or other forms of discontinuity occur. Practical applications include vibration absorbers, percussive drilling of hard materials, and dynamics of metal cutting. Of likely interest to new and experienced researchers working in the field of applied mathematics and physics, mechanical and civil engineering, and manufacturing. Lacks a subject index. Annotation copyrighted by Book News, Inc., Portland, OR.

Dynamics of Machines with Variable Mass - L Cveticanin 2022-02-14

Designed to be a complete and integrated text on the dynamic properties of machines, mechanisms, and rotors with variable mass, this book presents new results from investigations based on the general dynamics of systems with variable parameters. The book considers both weak and strong nonlinear vibrations of these systems, and chaotic phenomena are also discussed. The conservation laws and adiabatic invariants for systems with variable mass are formulated and the stability and instability conditions of motion are defined.

Mathematical Models of Exoskeleton - Andrey Valerievich Borisov 2022

This book presents the current state of the problem of describing the musculoskeletal system of a person. Models of the destruction of the endoskeleton and the restoration of its functions using exoskeleton are presented. A description is given of new approaches to modeling based on the use of weightless rods of variable length with concentrated masses. The practical application to the tasks of numerical simulation of the movements of the musculoskeletal system of a person is described. Exoskeleton models with variable-length units based on absolutely hard sections and sections that change their telescopic type length have been developed. The book is intended for specialists in the field of theoretical mechanics, biomechanics, robotics and related fields. The book will be useful to teachers, as well as graduate students, undergraduates and senior students of higher educational institutions, whose research interests lie in the modeling of anthropomorphic biomechanical systems.

Dynamics of Mechanical Systems with Non-Ideal Excitation - Livija Cveticanin 2017-07-01

In this book the dynamics of the non-ideal oscillatory system, in which the excitation is influenced by the response of the oscillator, is presented. Linear and nonlinear oscillators with one or more degrees of freedom interacting with one or more energy sources are treated. This concerns for example oscillating systems excited by a deformed elastic connection, systems excited by an unbalanced rotating mass, systems of parametrically excited oscillator and an energy source, frictionally self-excited oscillator and an energy source, energy harvesting system, portal frame - non-ideal source system, non-ideal rotor system, planar mechanism - non-ideal source interaction. For the systems the regular and irregular motions are tested. The effect of self-synchronization, chaos and methods for suppressing chaos in non-ideal systems are considered. In the book various types of motion control are suggested. The most important property of the non-ideal system connected with the jump-like transition from a resonant state to a non-resonant one is discussed. The so called 'Sommerfeld effect', resonant unstable state and jumping of the system into a new stable state of motion above the resonant region is explained. A mathematical model of the system is solved analytically and numerically. Approximate analytical solving procedures are developed. Besides, simulation of the motion of the non-ideal system is presented. The obtained results are compared with those for the ideal case. A significant difference is evident. The book aims to present the established results and to expand the literature in non-ideal vibrating systems. A further intention of the book is to give predictions of the effects for a system where the interaction between an oscillator and the energy source exist. The book is targeted at engineers and technicians dealing with the problem of source-machine system, but is also

written for PhD students and researchers interested in non-linear and non-ideal problems.

Effects of Internal Mass Flow on the Attitude Dynamics of Variable Mass Systems - Thy Tran 2003

Mechanical Systems, Classical Models - Petre P. Teodorescu 2008-09-24

As it was already seen in the first volume of the present book, its guideline is precisely the mathematical model of mechanics. The classical models which we refer to are in fact models based on the Newtonian model of mechanics, on its five principles, i. e. : the inertia, the forces action, the action and reaction, the parallelogram and the initial conditions principle, respectively. Other models, e. g. , the model of attraction forces between the particles of a discrete mechanical system, are part of the considered Newtonian model. Kepler's laws brilliantly verify this model in case of velocities much smaller than the light velocity in vacuum. The non-classical models are relativistic and quantic. Mechanics has as object of study mechanical

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Introduction to Space Dynamics - William Tyrrell Thomson 2012-09-11

Comprehensive, classic introduction to space-flight engineering for advanced undergraduate and graduate students provides basic tools for quantitative analysis of the motions of satellites and other vehicles in space.