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Linear State-Space Control Systems -

Robert L. Williams, II 2007-02-09

The book blends readability and accessibility common to undergraduate control systems texts with the mathematical rigor necessary to form a solid theoretical foundation.

Appendices cover linear algebra and provide a Matlab overview and files. The reviewers pointed out that this is an ambitious project but one that will pay off because of the lack of good up-to-date textbooks in the area.

Control System Engineering - Norman S. Nise 1998-01-15

The Second Edition of Control Systems Engineering provides a clear and thorough introduction to controls. Designed to motivate readers' understanding, the text emphasizes the practical application of systems engineering to the design and analysis of feedback systems. In a rich pedagogical style, Nise motivates readers by applying control systems theory and concepts to real-world problems. The text's updated content teaches readers to build control systems that can support today's advanced technology.

Discrete-time Control Systems - Katsuhiko Ogata 1995

A comprehensive treatment of the analysis

and design of discrete-time control systems which provides a gradual development of the theory by emphasizing basic concepts and avoiding highly mathematical arguments. The text features comprehensive treatment of pole placement, state observer design, and quadratic optimal control.

Technical Books in Print - 1974

Books in Print - 1991

Dynamic Modeling and Control of Engineering Systems - Bohdan T.

Kulakowski 2007-07-02

This textbook is ideal for a course in engineering systems dynamics and controls. The work is a comprehensive treatment of the analysis of lumped parameter physical systems. Starting with a discussion of mathematical models in general, and ordinary differential equations, the book covers input/output and state space models, computer simulation and modeling methods and techniques in mechanical, electrical, thermal and fluid domains. Frequency domain methods, transfer functions and frequency response are covered in detail.

The book concludes with a treatment of

stability, feedback control (PID, lead-lag, root locus) and an introduction to discrete time systems. This new edition features many new and expanded sections on such topics as: solving stiff systems, operational amplifiers, electrohydraulic servovalves, using Matlab with transfer functions, using Matlab with frequency response, Matlab tutorial and an expanded Simulink tutorial. The work has 40% more end-of-chapter exercises and 30% more examples.

Modern Control Engineering - Katsuhiko Ogata 1990

Text for a first course in control systems, revised (1st ed. was 1970) to include new subjects such as the pole placement approach to the design of control systems, design of observers, and computer simulation of control systems. For senior engineering students. Annotation copyright Book News, Inc.

Digital Control System Analysis and Design - Charles L. Phillips 1990

Simulation and Modeling Methodologies, Technologies and Applications - Mohammad S. Obaidat 2016-01-14

The present book includes a set of selected extended papers from the 4th International Conference on Simulation and Modeling Methodologies, Technologies and Applications (SIMULTECH 2014), held in Vienna, Austria, from 28 to 30 August 2014. The conference brought together researchers, engineers and practitioners interested in methodologies and applications of modeling and simulation. New and innovative solutions are reported in this book. SIMULTECH 2014 received 167 submissions, from 45 countries, in all continents. After a double blind paper review performed by the Program Committee, 23% were accepted as full papers and thus selected for oral presentation. Additional papers were accepted as short papers and posters. A further selection was made after the Conference, based also on the assessment of presentation quality and audience interest, so that this book includes the extended and revised versions of the very

best papers of SIMULTECH 2014.

Commitment to high quality standards is a major concern of SIMULTECH that will be maintained in the next editions, considering not only the stringent paper acceptance ratios but also the quality of the program committee, keynote lectures, participation level and logistics.

Modern Control Engineering - P.N. Paraskevopoulos 2017-12-19

"Illustrates the analysis, behavior, and design of linear control systems using classical, modern, and advanced control techniques. Covers recent methods in system identification and optimal, digital, adaptive, robust, and fuzzy control, as well as stability, controllability, observability, pole placement, state observers, input-output decoupling, and model matching."
Optimal Control Engineering with MATLAB - Rami A. Maher 2018

For control engineers, optimal control is a tool to design a primal controller which secures system stability and fulfils a certain set of specifications via the optimisation of a specific performance index. In this way, troublesome trial-and-error controller tuning procedures are avoided. The next step is to assess the possibility of practical implementation, and this usually leads to a need to implement some controller trade-offs. To this end, this book aims to construct bridges between conventional parameter optimisation and the methods of optimal control theory.

Modern Control System Theory and Design - Stanley M. Shinnars 1992-03-25

Offers unified treatment of conventional and modern continuous and discrete control theory and demonstrates how to apply the theory to realistic control system design problems. Along with linear and nonlinear, digital and optimal control systems, it presents four case studies of actual designs. The majority of solutions contained in the book and the problems at the ends of the chapters were generated using the commercial software package, MATLAB, and is available free to the users of the book by returning a postcard contained with the book to the MathWorks, Inc. This software

also contains the following features/utilities created to enhance MATLAB and several of the MathWorks' toolboxes: Tutorial File which contains the essentials necessary to understand the MATLAB interface (other books require additional books for full comprehension), Demonstration m-file which gives the users a feel for the various utilities included, OnLine HELP, Synopsis File which reviews and highlights the features of each chapter.

Advanced Control Engineering - Roland Burns 2001-11-07

Advanced Control Engineering provides a complete course in control engineering for undergraduates of all technical disciplines. Included are real-life case studies, numerous problems, and accompanying MatLab programs.

Scientific and Technical Books and Serials in Print - 1989

System Dynamics - William John Palm 2009-04-01

System Dynamics includes the strongest treatment of computational software and system simulation of any available text, with its early introduction of MATLAB and Simulink. The text's extensive coverage also includes discussion of the root locus and frequency response plots, among other methods for assessing system behavior in the time and frequency domains as well as topics such as function discovery, parameter estimation, and system identification techniques, motor performance evaluation, and system dynamics in everyday life.

Unmanned Aircraft Design - Mohammad Sadraey 2022-05-31

This book provides fundamental principles, design procedures, and design tools for unmanned aerial vehicles (UAVs) with three sections focusing on vehicle design, autopilot design, and ground system design. The design of manned aircraft and the design of UAVs have some similarities and some differences. They include the design process, constraints (e.g., g-load, pressurization), and UAV main components (autopilot, ground station, communication, sensors, and payload). A UAV designer must

be aware of the latest UAV developments; current technologies; know lessons learned from past failures; and they should appreciate the breadth of UAV design options. The contribution of unmanned aircraft continues to expand every day and over 20 countries are developing and employing UAVs for both military and scientific purposes. A UAV system is much more than a reusable air vehicle or vehicles. UAVs are air vehicles, they fly like airplanes and operate in an airplane environment. They are designed like air vehicles; they have to meet flight critical air vehicle requirements. A designer needs to know how to integrate complex, multi-disciplinary systems, and to understand the environment, the requirements and the design challenges and this book is an excellent overview of the fundamentals from an engineering perspective. This book is meant to meet the needs of newcomers into the world of UAVs. The materials are intended to provide enough information in each area and illustrate how they all play together to support the design of a complete UAV. Therefore, this book can be used both as a reference for engineers entering the field or as a supplementary text for a UAV design course to provide system-level context for each specialized topic.

Solutions Manual, Modern Control Engineering, Fourth Edition - Katsuhiko Ogata 2002

Modern Control Systems - Richard C. Dorf 2011

Modern Control Systems, 12e, is ideal for an introductory undergraduate course in control systems for engineering students. Written to be equally useful for all engineering disciplines, this text is organized around the concept of control systems theory as it has been developed in the frequency and time domains. It provides coverage of classical control, employing root locus design, frequency and response design using Bode and Nyquist plots. It also covers modern control methods based on state variable models including pole

placement design techniques with full-state feedback controllers and full-state observers. Many examples throughout give students ample opportunity to apply the theory to the design and analysis of control systems. Incorporates computer-aided design and analysis using MATLAB and LabVIEW MathScript.

Control System Design - Bernard Friedland 2012-03-08

Introduction to state-space methods covers feedback control; state-space representation of dynamic systems and dynamics of linear systems; frequency-domain analysis; controllability and observability; shaping the dynamic response; more. 1986 edition.

Proceedings of the 3rd International Conference on Intelligent Technologies and Engineering Systems (ICITES2014)

- Jengnan Juang 2015-11-12

This book includes the original, peer reviewed research from the 3rd International Conference on Intelligent Technologies and Engineering Systems (ICITES2014), held in December, 2014 at Cheng Shiu University in Kaohsiung, Taiwan. Topics covered include: Automation and robotics, fiber optics and laser technologies, network and communication systems, micro and nano technologies and solar and power systems. This book also Explores emerging technologies and their application in a broad range of engineering disciplines Examines fiber optics and laser technologies Covers biomedical, electrical, industrial and mechanical systems Discusses multimedia systems and applications, computer vision and image & video signal processing

System Dynamics - Katsuhiko Ogata 2013-07-24

For junior-level courses in System Dynamics, offered in Mechanical Engineering and Aerospace Engineering departments. This text presents students with the basic theory and practice of system dynamics. It introduces the modeling of dynamic systems and response analysis of these systems, with an introduction to the analysis and design of control systems.

Optimal Control Theory - Donald E. Kirk

2012-04-26

Upper-level undergraduate text introduces aspects of optimal control theory: dynamic programming, Pontryagin's minimum principle, and numerical techniques for trajectory optimization. Numerous figures, tables. Solution guide available upon request. 1970 edition.

Modern Control Engineering - Maxwell Noton 2014-06-20

Modern Control Engineering focuses on the methodologies, principles, approaches, and technologies employed in modern control engineering, including dynamic programming, boundary iterations, and linear state equations. The publication first ponders on state representation of dynamical systems and finite dimensional optimization. Discussions focus on optimal control of dynamical discrete-time systems, parameterization of dynamical control problems, conjugate direction methods, convexity and sufficiency, linear state equations, transition matrix, and stability of discrete-time linear systems. The text then tackles infinite dimensional optimization, including computations with inequality constraints, gradient method in function space, quasilinearization, computation of optimal control-direct and indirect methods, and boundary iterations. The book takes a look at dynamic programming and introductory stochastic estimation and control. Topics include deterministic multivariable observers, stochastic feedback control, stochastic linear-quadratic control problem, general calculation of optimal control by dynamic programming, and results for linear multivariable digital control systems. The publication is a dependable reference material for engineers and researchers wanting to explore modern control engineering.

Modern Control Engineering - Katsuhiko Ogata 1970

This comprehensive treatment of the analysis and design of continuous-time control systems provides a "gradual" development of control theory and shows how to solve "all" computational problems with MATLAB. It avoids highly mathematical

arguments, and features an abundance of examples and worked problems throughout the book. Chapter topics include the Laplace transform; mathematical modeling of mechanical systems, electrical systems, fluid systems, and thermal systems; transient and steady-state-response analyses, root-locus analysis and control systems design by the root-locus method; frequency-response analysis and control systems design by the frequency-response; two-degrees-of-freedom control; state space analysis of control systems and design of control systems in state space. For control systems engineers.

Scientific and Technical Books in Print - 1972

Modern Control Systems Engineering - Zoran Gajic 1996

The book represents a modern treatment of classical control theory and application concepts. Theoretically, it is based on the state-space approach, where the main concepts have been derived using only the knowledge from a first course in linear algebra. Practically, it is based on the MATLAB package for computer-aided control system design, so that the presentation of the design techniques is simplified. The inclusion of MATLAB allows deeper insights into the dynamical behaviour of real physical control systems, which are quite often of high dimensions. Continuous-time and discrete-time control systems are treated simultaneously with a slight emphasis on the continuous-time systems, especially in the area of controller design. Instructor's Manual (0-13-264730-3).

Intelligent Control Systems with an Introduction to System of Systems Engineering - Thrishantha Nanayakkara 2018-09-03

From aeronautics and manufacturing to healthcare and disaster management, systems engineering (SE) now focuses on designing applications that ensure performance optimization, robustness, and reliability while combining an emerging group of heterogeneous systems to realize a common goal. Use SoS to Revolutionize

Management of Large Organizations, Factories, and Systems Intelligent Control Systems with an Introduction to System of Systems Engineering integrates the fundamentals of artificial intelligence and systems control in a framework applicable to both simple dynamic systems and large-scale system of systems (SoS). For decades, NASA has used SoS methods, and major manufacturers—including Boeing, Lockheed-Martin, Northrop-Grumman, Raytheon, BAE Systems—now make large-scale systems integration and SoS a key part of their business strategies, dedicating entire business units to this remarkably efficient approach. Simulate Novel Robotic Systems and Applications Transcending theory, this book offers a complete and practical review of SoS and some of its fascinating applications, including: Manipulation of robots through neural-based network control Use of robotic swarms, based on ant colonies, to detect mines Other novel systems in which intelligent robots, trained animals, and humans cooperate to achieve humanitarian objectives Training engineers to integrate traditional systems control theory with soft computing techniques further nourishes emerging SoS technology. With this in mind, the authors address the fundamental precepts at the core of SoS, which uses human heuristics to model complex systems, providing a scientific rationale for integrating independent, complex systems into a single coordinated, stabilized, and optimized one. They provide readers with MATLAB® code, which can be downloaded from the publisher's website to simulate presented results and projects that offer practical, hands-on experience using concepts discussed throughout the book. Modern Control Theory - William L. Brogan 1982

Automatic Control - Benjamin C. Kuo 1995-01-15

This best-selling introduction to automatic control systems has been updated to reflect the increasing use of computer-aided learning and design, and revised to feature a more accessible approach — without

sacrificing depth.

Orbital Mechanics for Engineering

Students - Howard D Curtis 2009-10-26
Orbital Mechanics for Engineering Students, Second Edition, provides an introduction to the basic concepts of space mechanics. These include vector kinematics in three dimensions; Newton's laws of motion and gravitation; relative motion; the vector-based solution of the classical two-body problem; derivation of Kepler's equations; orbits in three dimensions; preliminary orbit determination; and orbital maneuvers. The book also covers relative motion and the two-impulse rendezvous problem; interplanetary mission design using patched conics; rigid-body dynamics used to characterize the attitude of a space vehicle; satellite attitude dynamics; and the characteristics and design of multi-stage launch vehicles. Each chapter begins with an outline of key concepts and concludes with problems that are based on the material covered. This text is written for undergraduates who are studying orbital mechanics for the first time and have completed courses in physics, dynamics, and mathematics, including differential equations and applied linear algebra. Graduate students, researchers, and experienced practitioners will also find useful review materials in the book. NEW: Reorganized and improved discussions of coordinate systems, new discussion on perturbations and quaternions NEW: Increased coverage of attitude dynamics, including new Matlab algorithms and examples in chapter 10 New examples and homework problems

Books in Print Supplement - 1985

Feedback Control of Dynamic Systems -

Gene F. Franklin 2011-11-21

This is the eBook of the printed book and may not include any media, website access codes, or print supplements that may come packaged with the bound book. For senior-level or first-year graduate-level courses in control analysis and design, and related courses within engineering, science, and management. Feedback Control of Dynamic

Systems, Sixth Edition is perfect for practicing control engineers who wish to maintain their skills. This revision of a top-selling textbook on feedback control with the associated web site, FPE6e.com, provides greater instructor flexibility and student readability. Chapter 4 on A First Analysis of Feedback has been substantially rewritten to present the material in a more logical and effective manner. A new case study on biological control introduces an important new area to the students, and each chapter now includes a historical perspective to illustrate the origins of the field. As in earlier editions, the book has been updated so that solutions are based on the latest versions of MATLAB and SIMULINK. Finally, some of the more exotic topics have been moved to the web site.

Digital Control Engineering - M. Sami Fadali 2012-08-21

Digital controllers are part of nearly all modern personal, industrial, and transportation systems. Every senior or graduate student of electrical, chemical or mechanical engineering should therefore be familiar with the basic theory of digital controllers. This new text covers the fundamental principles and applications of digital control engineering, with emphasis on engineering design. Fadali and Visioli cover analysis and design of digitally controlled systems and describe applications of digital controls in a wide range of fields. With worked examples and Matlab applications in every chapter and many end-of-chapter assignments, this text provides both theory and practice for those coming to digital control engineering for the first time, whether as a student or practicing engineer. Extensive Use of computational tools: Matlab sections at end of each chapter show how to implement concepts from the chapter Frees the student from the drudgery of mundane calculations and allows him to consider more subtle aspects of control system analysis and design An engineering approach to digital controls: emphasis throughout the book is on design of control systems. Mathematics is used to help explain concepts, but throughout the

text discussion is tied to design and implementation. For example coverage of analog controls in chapter 5 is not simply a review, but is used to show how analog control systems map to digital control systems

Review of Background Material: contains review material to aid understanding of digital control analysis and design. Examples include discussion of discrete-time systems in time domain and frequency domain (reviewed from linear systems course) and root locus design in s-domain and z-domain (reviewed from feedback control course)

Inclusion of Advanced Topics In addition to the basic topics required for a one semester senior/graduate class, the text includes some advanced material to make it suitable for an introductory graduate level class or for two quarters at the senior/graduate level. Examples of optional topics are state-space methods, which may receive brief coverage in a one semester course, and nonlinear discrete-time systems

Minimal Mathematics Prerequisites The mathematics background required for understanding most of the book is based on what can be reasonably expected from the average electrical, chemical or mechanical engineering senior. This background includes three semesters of calculus, differential equations and basic linear algebra. Some texts on digital control require more

Matlab for Control Engineers - Katsuhiko Ogata 2008

For senior-level courses in Control Theory, offered by departments of Electrical & Computer Engineering or Mechanical & Aerospace Engineering. Notable author Katsuhiko Ogata presents the only book available to discuss, in sufficient detail, the details of MATLAB(R) materials needed to solve many analysis and design problems associated with control systems. In this new text, Ogata complements a large number of examples with in-depth explanations, encouraging complete understanding of the MATLAB approach to solving problems. The book's flexible presentation makes it ideal for use as a stand-alone text for those

wishing to expand their knowledge of MATLAB; it can also be used in conjunction with a wide range of currently available control textbooks

Optimal Sample Policies for Multirate Digital Control - Michael Lee Narigon 1991

Control System Design - Graham Clifford Goodwin 2001

For both undergraduate and graduate courses in Control System Design. Using a "how to do it" approach with a strong emphasis on real-world design, this text provides comprehensive, single-source coverage of the full spectrum of control system design. Each of the text's 8 parts covers an area in control--ranging from signals and systems (Bode Diagrams, Root Locus, etc.), to SISO control (including PID and Fundamental Design Trade-Offs) and MIMO systems (including Constraints, MPC, Decoupling, etc.).

Advanced Modern Control System Theory and Design - Stanley M. Shinnars 1998-09-30

The definitive guide to advanced control system design Advanced Modern Control System Theory and Design offers the most comprehensive treatment of advanced control systems available today. Superbly organized and easy to use, this book is designed for an advanced course and is a companion volume to the introductory text, Modern Control System Theory and Design, Second Edition (or any other introductory book on control systems). In addition, it can serve as an excellent text for practicing control system engineers who need to learn more advanced control systems techniques in order to perform their tasks. Advanced Modern Control Systems Theory and Design briefly reviews introductory control system analysis concepts and then presents the methods for designing linear control systems using single-degree and two-degrees-of-freedom compensation techniques. The very important subjects of modern control system design using state-space, pole placement, Ackermann's formula, estimation, robust control, and H8 techniques are then presented. The

following crucial subjects are then covered in the presentation: * Digital Control System Analysis and Design-extends the continuous concepts presented to discrete systems * Nonlinear Control System Design-extends the linear concepts presented to nonlinear systems * Introduction to Optimal Control Theory and Its Applications-presents such key topics as dynamic programming and the maximum principle, as well as applications to the space attitude control problem and the lunar soft-landing problem * Control System Design Examples: Complete Case Studies-presents the complete case studies of five control system design examples that illustrate practical design projects Other notable features of this volume are: * Free MATLAB software containing problem solutions which can be retrieved from the Mathworks, Inc. anonymous FTP server at <ftp://ftp.mathworks.com/pub/books/advshiners> * MATLAB programs and a tutorial on the use of MATLAB incorporated directly into the text * An extensive set of worked-out, illustrative solutions added in dedicated sections at the end of chapters * End-of-chapter problems-one-third with answers to facilitate self-study * A solutions manual containing solutions to the remaining two-thirds of the problems available from the Wiley editorial department.

The Publishers' Trade List Annual - 1981

Computational Aids in Control Systems Using MATLAB - Hadi Saadat 1993

Accompanying computer disk contains functions and examples developed by the author.

Feedback Systems - Karl Johan Åström
2021-02-02

The essential introduction to the principles and applications of feedback systems—now fully revised and expanded This textbook covers the mathematics needed to model, analyze, and design feedback systems. Now more user-friendly than ever, this revised and expanded edition of Feedback Systems is a one-volume resource for students and researchers in mathematics and engineering. It has applications across a range of disciplines that utilize feedback in physical, biological, information, and economic systems. Karl Åström and Richard Murray use techniques from physics, computer science, and operations research to introduce control-oriented modeling. They begin with state space tools for analysis and design, including stability of solutions, Lyapunov functions, reachability, state feedback observability, and estimators. The matrix exponential plays a central role in the analysis of linear control systems, allowing a concise development of many of the key concepts for this class of models. Åström and Murray then develop and explain tools in the frequency domain, including transfer functions, Nyquist analysis, PID control, frequency domain design, and robustness. Features a new chapter on design principles and tools, illustrating the types of problems that can be solved using feedback Includes a new chapter on fundamental limits and new material on the Routh-Hurwitz criterion and root locus plots Provides exercises at the end of every chapter Comes with an electronic solutions manual An ideal textbook for undergraduate and graduate students Indispensable for researchers seeking a self-contained resource on control theory